

# Avionics

## GPSG-1000

GPS/Galileo Portable Positional Simulator

**AEROFLEX**  
A passion for performance.



Versatile time-saving portable test set for GPS/GALILEO receivers

- GPS signals simulated: L1, L1C\*, L2C\*, L5
- Galileo signals simulated: E1, E5, E5a, E5b\*
- Simultaneous GPS/Galileo simulation
- SBAS satellites simulated:
  - WAAS/EGNOS L1, L5
- Static or multi-leg dynamic positional simulation via route & waypoint entry system
- 6 or 12 channel configurations available with upgrade path (RAIM supported)
- Programmable space vehicle (SV) parametrics and health
- User or built-in GPS receiver referenced time and date
- Digital noise generation for direct connect testing of receiver
- Large color touch-screen display with simple user interface
- Remote control interface Ethernet
- A-GPS Option (Aeroflex 4400 support)\*\*

\* Phase III software release

\*\* Contact factory for availability

### General

The GPSG-1000 is a single carrier, multi-channel simulator designed to be software upgradable.

### Applications

- General testing of civil GPS and Galileo receivers
- Limited testing of military GPS receivers, L1 C/A code or L1 (P)Y pseudo code only



### Channels

The six channel GPSG-1000 configuration provides 3D positional simulation with five channels for RAIM operation and one channel may be allocated to SBAS simulation.

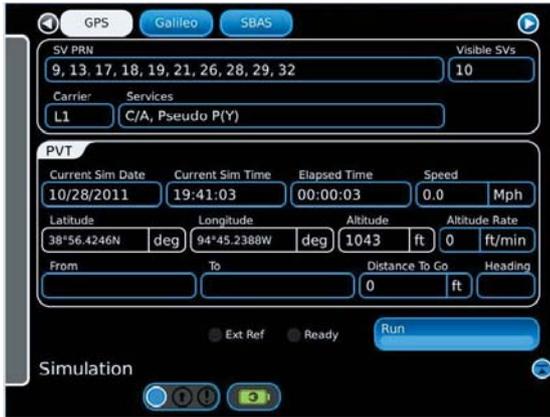
The twelve channel GPSG-1000 configuration provides the same capability as the six channel unit, plus six additional channels. This allows any combination of visible SVs to be selected. One, two or three channels may be allocated to SBAS simulation.

For the very latest specifications visit [www.aeroflex.com](http://www.aeroflex.com)

## Simulation

The Simulation page shows the selected GNSS signals generated and provides a PVT (Position, Velocity and Time) display. The data displayed also includes the current waypoint leg, heading and distance to go.

In the Static mode of operation, a 3D position may be user entered in Latitude/Longitude/Height format. Almanac data is derived either from the built-in L1 C/A Code GPS receiver or via an external file load. Positional simulation may also be synchronized to UTC via the receiver.



## SV Selection

All GPSG-1000 configurations allow GPS and Galileo satellites to be mixed. SVs are allocated automatically for optimal geometry according to simulated position. The user may turn off individual SVs, to create scenarios with poor geometry for RAIM testing.

Each SV may have Doppler, Amplitude, Step Error and Code Carrier Coherence parameters deviated from nominal and Satellite Health set.

Signal Fading and Dynamic Signal Amplitude and Simulator RF level may be applied to all satellites.



## SBAS

SBAS satellites WAAS/EGNOS are automatically allocated based on simulated position. The user can select the number of SBAS SVs that can be allocated and can selectively turn off individual SVs.

## Waypoints

Waypoints may be created and stored in Latitude/Longitude/Altitude form or automatically recalled from the provided waypoint data base organized by an airport or city. Waypoints may be selected for inclusion in a route in dynamic mode or as a single position in static mode.



## Routes

In the Dynamic position mode of operation, the Route page may be used to sequentially enter user defined route points. Routes comprising of up to 99 route points, may be saved and recalled under a user entered route name, using the route file management system. Route points can be reordered, edited or deleted. 3D position data comprising Latitude, Longitude and Altitude may be manually entered, or selected from the waypoints page. Additional parameters that define a route point are.. Speed, Linear Acceleration and Altitude Rate. Turns may be executed at the route point, utilizing a user defined Turn Radius. Realistic turns are maintained to 10G.



## Setup

The Setup page is partitioned via a tab selection scheme to allow control for Simulation, Almanac, Channels and I/O.

The simulation tab provides controls for GNSS System Selection and Carrier, also Digital Noise, Multipath (fading) model selection, PRN RF Signal levels, Position Source, Simulation Type and SBAS.



## File

The file management system is partitioned via a tab selection scheme. File management is provided for almanacs, routes and simulator settings. Facilities include loading, storage, and naming of files.



## A-GPS (Assisted GPS) – Option\*\*

The A-GPS option allows the GPSG-1000 to be used in conjunction with the Aeroflex 4400 CDMA Mobile Phone Tester, to provide a comprehensive test of the mobile phone built-in GPS receiver using the A-GPS protocols.



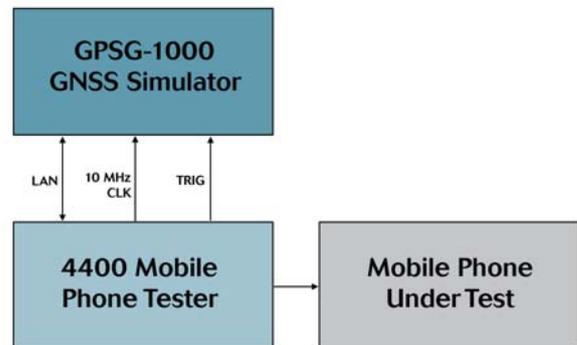
The GPSG-1000 provides a predefined scenario 62.5 min, or 5 navigation messages in length. Three data files are created after an initial real-time run of the simulation, which are provided over the Ethernet interface via a set of remote commands. The files are:

Acquisition: Time stamped data

Processed Navigation Data: Time stamped almanac and ephemeris data in engineering units

Raw Navigation Data: (5 messages) used for sensitivity assistance

The GPSG-1000 can store the scenarios and the relevant files generated in simulator memory using the settings storage facility provided in the GPSG-1000 GUI.



The 4400 utilizes the three file types, which are in a time stamped format, for creating assistance data that is sent to the phone under test upon request. The 4400, via the Ethernet interface, can arm the GPSG-1000 simulation and provide a hardware trigger of the simulation. The GPSG-1000 external 10 MHz clock is provided by the 4400, allowing the synchronization of the RF simulation with the data used in the simulation, stored in the 4400 memory.

For more information about the Aeroflex 4400, please use the following link:

[http://www.aeroflex.com/ats/products/product/Communications\\_Test/Cellular\\_Parametric\\_Test/4400\\_Mobile\\_Phone\\_Tester\\_Series--756.html#](http://www.aeroflex.com/ats/products/product/Communications_Test/Cellular_Parametric_Test/4400_Mobile_Phone_Tester_Series--756.html#)

\*\* Contact factory for availability

# GENERAL SPECIFICATIONS

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## USER INTERFACE

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### Display

12" color LCD, sunlight readable with back light

### Controls

Touch screen

## ANTENNA COUPLER

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### Antenna Coupler

Cavity, patch

### Coupling

21 dB typical at 1575.42 MHz

### Isolation

>25 dB at 1575.42 MHz

>30 dB typical at 1575.42 MHz

## DIRECT CONNECTION PORTS

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### Impedance

50  $\Omega$

### SWR

1.3:1 maximum

### Connector

TNC x 2

### Coupling

AC (maximum DC input 50 V)

## GENERATOR

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### GPS Frequencies

L1: 1575.42 MHz (C/A, pseudo P(Y), SBAS)

L1C\*: 1575.42 MHz

L2C\*: 1227.60 MHz

L5: 1176.45 MHz (New Civil SoL)

### Galileo Frequencies

E1: 1575.420 MHz (pseudo-PRS, [pseudo-G/NAV]), (OS, CS, SoL, [I/NAV])

E5: 1191.795 MHz center frequency

E5a: 1176.45 MHz (OS, (F/NAV))

E5b\*: 1207.14 MHz (CS, SoL, (I/NAV))

### Glonass (future use)

1602 MHz (center)

### Accuracy

Same as master oscillator

### Inter Channel Bias

Zero (digital design)

\* Phase III software release

### Frame Sync Output

LVTTL

### Channels

1-6, 1-12 SV simulation, selectable

GPS: PRN=1 to 32

Galileo: PRN=1 to 36

SBAS: PRN=120 to 138.

Positional simulation via menu entry of Latitude and Longitude or positional offset and waypoint.

### Positional Simulation

Static: Via user entry of Latitude/Longitude/Altitude or selectable from waypoint database.

Dynamic: Create, store and recall routes consisting of multiple route points.

### User Defined Doppler Error

Selectable frequency offset  $\pm 5.0$  kHz, 1 Hz increment

### Amplitude Offset

Sets SV carrier amplitude offset from main attenuator setting  $\pm 15$  dB in 1 dB increments.

### Step Error

Sets SV pseudo range error  $\pm 10$  km in 1 m increments (used for RAIM testing)

### Satellite Health

Allows selection of GOOD or BAD

### Code Carrier Coherence

Sets frequency variation between code carriers

Range 2 m/S

Increment 1 mm/S

## GPS CODES

### L1 C/A

#### Code Rate

1.023 Mc/s

#### Primary Sequence Length

1023 bits

#### Modulation

BPSK

#### Symbol Rate

50 sps

### SBAS

WAAS/EGNOS L1, L5

### L2C\*

#### Code Rate

0.5115 Mc/s

#### Sequence Length

10230/767250 bits

#### Modulation

BPSK

#### Symbol Rate

50 sps

## L1 (P)Y (not encrypted)

### Code Rate

10.230 Mc/s

### Sequence Length

15345000 bits

### Modulation

BPSK

Note: Long random codes simulated

## L1C\*

### Code Rate

10.230 Mc/s

### Sequence Length

10230 bits

### Modulation

BOC (1, 1)

## L5

### Code Rate

10.230 Mc/s

### Sequence Length

10230 bits

### Modulation

QPSK

## GALILEO SERVICES

### E1

#### Pseudo G/NAV

Long random codes simulated

#### Code Rate

2.5575 Mc/s

#### Sequence Length

TBC

#### Symbol Rate

TBC

#### Modulation

Interplex/CBOC

#### Sub Modulation

BOC (15,2.5)

Note: PRS not supported

### E1

#### OS

Complete implementation (I/NAV)

\* Phase III software release

## CS

Null message content (pseudo I/NAV)

## SoL

Compliant, no integrity alerts (I/NAV)

### Code Rate

1.023 Mc/s

### Sequence Length

4092 (primary) x 1 (secondary) bits

### Symbol Rate

250 sps

### Modulation

Interplex/CBOC

### Sub Modulation

CBOC(6,1,1)

## E5a

### OS

Complete implementation (F/NAV)

### Code Rate

10.23 Mc/s

### Sequence Length

10230 (primary) x 20 (secondary) bits

### Symbol Rate

50 sps

### Modulation

ALTBOC

### Sub Modulation

None

## E5b\*

### OS

Complete implementation (F/NAV)

## CS

Null message content (pseudo I/NAV)

## SoL

Compliant, no integrity alerts (I/NAV)

### Code Rate

10.23 Mc/s

### Sequence Length

10230 (primary) x 4 (secondary) bits

### Symbol Rate

250 sps

### Modulation

ALTBOC

### Sub Modulation

None

## Almanac

Obtainable from built-in GPS receiver or external file load in .alm format.

## NAV Data

Navigation data is computed in real-time to match the simulation.

## Positional Simulation

### Maximum Relative Velocity

$\pm 1000$  Kts (514 m/s)

### Maximum Relative Acceleration

$\pm 50$  m/s<sup>2</sup>

### Maximum Relative Jerk

$\pm 20$  m/s<sup>3</sup>

### Maximum Altitude

60,000 ft.

## Error Models

Atmospheric

\*\* Contact factory for availability

## Positional Simulation Accuracy

### Pseudorange

<0.1 m

### Pseudorange Rate

$\pm 0.01$  m/s (RMS) with respect to master oscillator

## RF Output Level

### Direct

-93 to -155 in 1 dB step

### ANT Coupler

-68 to -130 in 1 dB step

$\pm 2$  dB accuracy into 50  $\Omega$  (AC coupled) standard cable, 4 dB loss

## Signal Quality

### Spurious

<-35 dBc over the bandwidth (40 MHz)

### Harmonics

<-45 dBc

## A-GPS OPTION\*\*

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Simulation run time 62.5 min (5 navigation messages)

### Simulation Trigger

LVTTL Input

### Simulation Data Files

Acquisition (time stamped)

Processed Navigation Data - almanac and ephemeris (time stamped)

Raw Navigation Data

## MASTER OSCILLATOR

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### Frequency

10 MHz nominal

### Temperature Stability

$\pm 0.05$  ppm

## Aging Rate

$\pm 0.3$  ppm/yr,  $\pm 2.5$  ppm/ 10 yr.

## Uncertainty

$\pm 1$  ppm

## External Reference Input

### Input Level

0.25 to 6.0 Vp-p

### Input Impedance

50 ohm nominal

### Input Frequency

10.0 MHz  $\pm 10$  Hz

## External Reference Output

### Output Level

1.5 Vp-p nominal into 50  $\Omega$

### Output Frequency

10.0 MHz nominal

## BATTERY

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14.8V 6.6Ah Lithium Ion

### Battery Temperature Range for Charging

0° to 45°C

## ENVIRONMENTAL

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### Test Set Certifications

#### Operational Temperature

$-20^{\circ} \leq T \leq 55^{\circ} \text{C}$

#### Storage Temperature

$-30^{\circ} \leq T \leq 71^{\circ} \text{C}$

#### Operational Humidity

MIL-PRF-28800F Class 2

#### Storage Humidity

MIL-PRF-28800F Class 2

#### Altitude

$\leq 10,000$  feet

#### Vibration Limits

MIL-PRF-28800F Class 2

#### Shock, Functional

MIL-PRF-28800F Class 2

#### Transit Drop

MIL-PRF-28800F Class 2

#### Drip Proof

MIL-PRF-28800F Class 2

#### Dust

MIL-PRF-28800F Class 2

#### Salt

MIL-PRF-28800F Class 2

#### Explosive Atmosphere

MIL-STD-810F Method 511.4, Procedure 1

### Safety Compliance

UL-61010:2001

### CSA 22.2 No 1010.1

### WEEE

### ROHS

### EMC

#### Emissions

MIL-PRF28800F Class 2

EN 61326:1998 Class A

EN 61000-3-2

EN 61000-3-3

#### Immunity

MIL-PRF28800F Class 2

EN 61326:1998 Class A

### External AC-DC Converter Certifications

#### Safety Compliance

UL 1950 DS

CSA 22.2 No. 234

VDE EN 60 950

EMI/RFI Compliance FCC Docket 20780 Curve "B"

EMC EN 61326

### Transit Case Certifications

Drop Test FED-STD-101C Method 5007.1

Paragraph 6.3, Procedure A, Level A

Falling Dart Impact ATA 300 Category I

Vibration, Loose Cargo FED-STD-101C Method 5019

Vibration, Sweep ATA 300 Category I

Simulated Rainfall MIL-STD-810F Method 506.4 Procedure II of 4.1.2

FED-STD-101C Method 5009.1 Sec 6.7.1

Immersion MIL-STD-810F Method 512.4

## ENVIRONMENTAL (SUPPLIED EXTERNAL AC TO DC CONVERTER)

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### Use

Indoors

### Altitude

≤10,000 feet

### Operating Temperature

5°C to 40°C

### Storage Temperature

-20°C to 71°C

## PHYSICAL CHARACTERISTICS

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### GPSG-1000

#### Height

10.63 in. (27.0 cm)

#### Width

13.97 in. (35.5 cm)

### Depth

3.425 in. (8.7 cm)

### Weight (Test set only)

<10 lbs. (4.5 kg)

### ANTENNA COUPLER

#### Height

7.54 in. (191.5 cm)

#### Width

7.46 in. (189.5 cm)

#### Depth

7.46 in. (189.5 cm)

(Note: Maximum antenna height accommodated 1.5 in)

### RF Gasket

Flexible seal

### Connector

TNC

### Positioning

By hand or with optional 8ft placement pole via hook.

### Placement Security

Weighted peripheral bag



## ***VERSIONS, OPTIONS AND ACCESSORIES***

<b>Ordering Number</b>	<b>Description</b>
87339	GPSG-1000 6 Satellite Simulator
87715	GPSG-1000 12 Satellite Option
89475	GPSG-1000 A-GPSG Option**

### **Standard Accessories**

88493	Transit case (qty 1)
67374	Power supply
87636	Antenna coupler
90113	RX Antenna
90114	Cable, coax 50 ft.
62302	Power cord (U.S)
64020	Power cord (European)
88037	Operation Manual (CD)
88038	Getting Started Manual (paper)

### **Optional Accessories**

87040	External battery charger
86196	Spare battery pack
90106	Kit, Antenna coupler placement pole 8 ft.
89023	Maintenance Manual (CD)**

\*\* Contact factory for availability

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Our passion for performance is defined by three attributes represented by these three icons: solution-minded, performance-driven and customer-focused.